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***Ex-situ* TS measurements of juvenile yellowfin (*Thunnus albacares*) and frequency-response discrimination of three tropical tuna species**

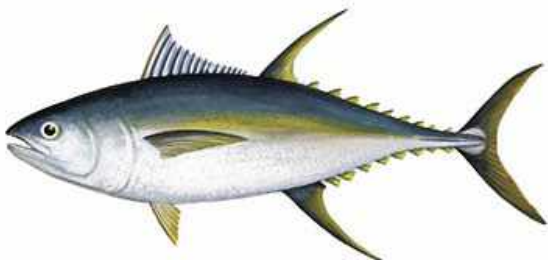
Bea Sobradillo, Guillermo Boyra, Jon Uranga, Iker Urtizberea, Udane Martínez and Gala Moreno



Skipjack (*Katsuwonus pelamis*)



Bigeye (*Thunnus obesus*)



Yellowfin (*Thunnus albacares*)

Tropical tuna in DFADs

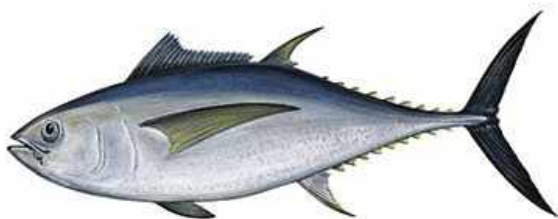
More than half of the purse seine landings aiming at tropical tuna come from fishing with **Fish Aggregating Devices** (DFADs), equipped with scientific echo-sounders to provide remote information on the aggregated biomass.

Using **acoustic** equipment before the nets are set improves the **selectivity** of the catch.

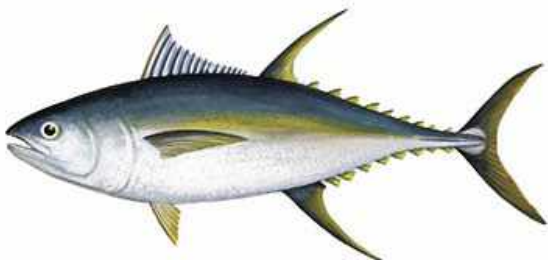
There are mainly **three** tropical tuna species that can be found simultaneously aggregated in FADs.



Skipjack (*Katsuwonus pelamis*)



Bigeye (*Thunnus obesus*)



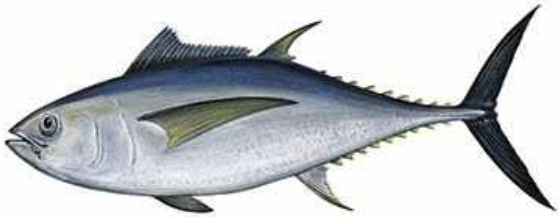
Yellowfin (*Thunnus albacares*)

Acoustic species discrimination

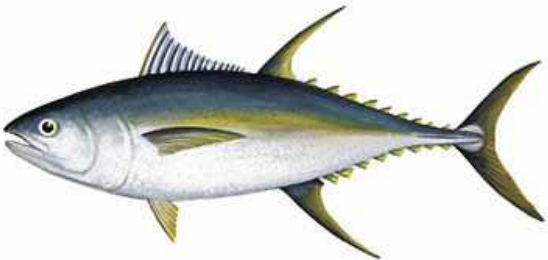
1. Determine sound scattering properties of each species separately, mainly the **Target strength** (dB re 1m²)
2. Determine the **frequency response** of each species
3. Develop a **species discrimination algorithm**



Skipjack (*Katsuwonus pelamis*)



Bigeye (*Thunnus obesus*)



Yellowfin (*Thunnus albacares*)

Target strength: logarithmic measure of the proportion of the incident energy that is backscattered by the target (σ).

$$TS = 10 \log_{10} \sigma$$

$$Number = Vol * \frac{S_v}{\sigma}$$

TS is mainly affected by:

- Fish (or swimbladder) length: **b20**
- Tilt angle relative to the beam centered axis
- Depth range due to pressure effect on swimbladder
- Distance from the transducer: nearfield effect, point source violation...



Skipjack
Katsuwonus pelamis



Original Article

Target strength of skipjack tuna (*Katsuwonus pelamis*) associated with fish aggregating devices (FADs)

Guillermo Boyra^{1*}, Gala Moreno², Bea Sobradillo³, Isabel Pérez-Arjona⁴, Igor Sancristobal¹, and David A. Demer⁵



Bigeye
Thunnus obesus



In situ target strength of bigeye tuna (*Thunnus obesus*) associated with fish aggregating devices

G. Boyra^{1*}, G. Moreno², B. Orue³, B. Sobradillo³, and I. Sancristobal⁵



RESEARCH ARTICLE

Towards acoustic discrimination of tropical tuna associated with Fish Aggregating Devices

Gala Moreno^{1*}, Guillermo Boyra², Igor Sancristobal³, David Itano⁴, Victor Restrepo¹

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Acoustic species discrimination

Determine sound scattering properties of each species separately, mainly the **Target strength** (dB re 1m²)

Determine the **frequency response** of each species

Develop a **species discrimination algorithm**



Ex-situ TS measurements of juvenile yellowfin (*Thunnus albacares*) and frequency-response discrimination of three tropical tuna species

Bea Sobradillo ¹, Guillermo Boyra ², Jon Uranga ² and Gala Moreno ³

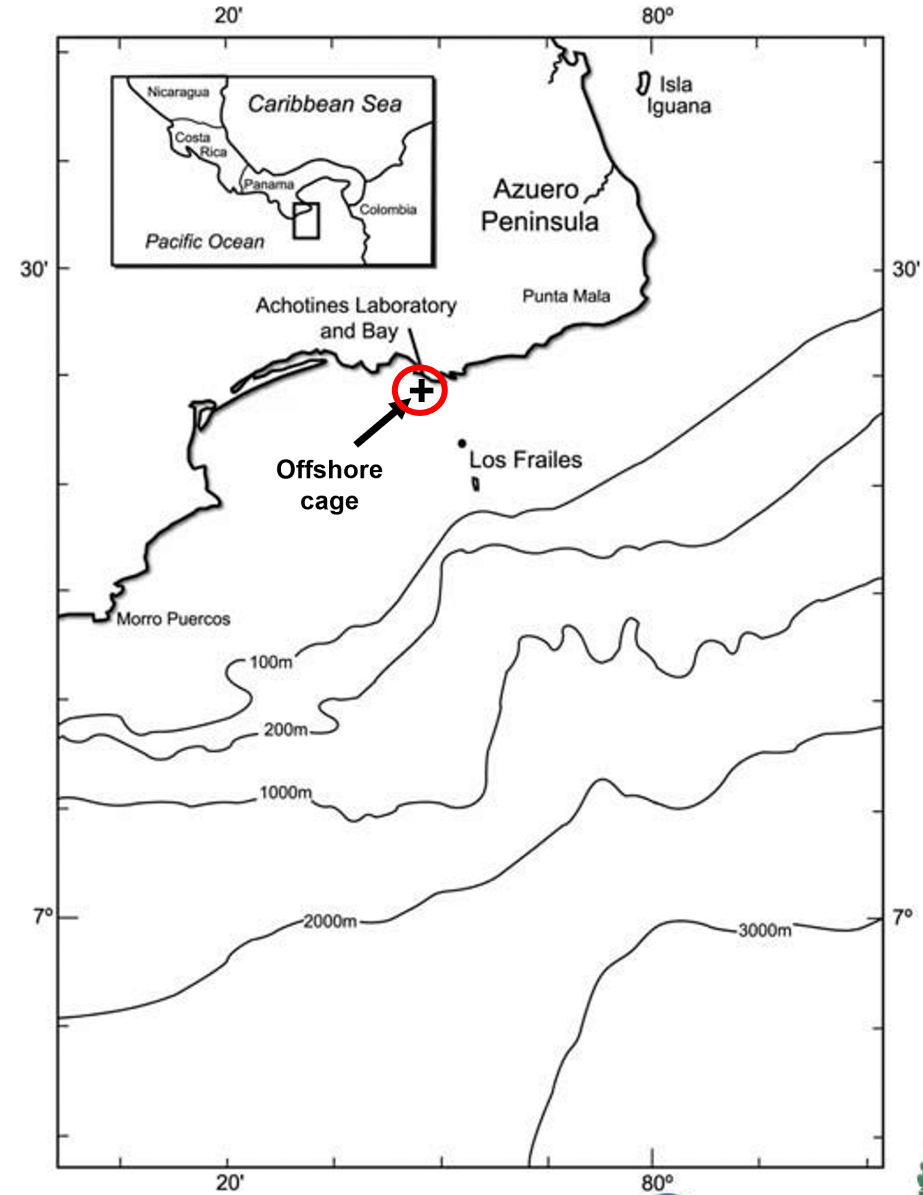
Acoustic species discrimination

- ➔ Determine sound scattering properties of each species separately, mainly the **Target strength** (dB re 1m²)
- ➔ Determine the **frequency response** of each species
- ➔ Develop a **species discrimination algorithm**

Achotines laboratory

Set 1: July 2016

Set 2: May-June 2022



Achotines laboratory



Acoustic sampling

- Steel floating plate stable below surface with Simrad EK80 38, 70, 120 and 200 kHz transducers.
- Acoustic equipment (transceivers, electronic devices) installed on a vessel.
- Emitted pulse duration: 0.512 ms, CW mode
- Calibration prior to data collection (*Demer et al., 2015*)
- Depth range: 10 – 25 m
 - Nearfield:
 - 38 kHz transducer: **4.55 m**
 - Swimbladder at 200 kHz: **3.9 m**
 - Beam diameter = largest fish length insonified at **7 m**
 - Point source violation avoidance

} **8.45 m**



Table 1. Biological measurements from fish body (TL: total length, FL: fork length, width, height and weight), and swimbladder. Z is the depth at which the diameter of the acoustic beam cross-section equals the fish or swimbladder length. Specimen marked with (*) is dead and used for controlled range experiment.

Year	Set	Fish						Swimbladder			
		TL cm	FL cm	Z m	Width cm	Height cm	Weight kg	Length cm	Z m	Width cm	Area cm ²
2016	1	57	51.9	4.7	9.5	13	2.9	11.4	0.9	3.1	28.0
2016	1	70.8	64.4	5.8	11	15	3.9	12.2	1.0	4.1	38.8
2016	1	45.2	41.1	3.7	7.5	10.5	1.52	9.3	0.8	2.7	19.8
2016	1	59	53.7	4.8	10	13.5	3.16	12.5	1.0	3.8	37.6
2022	1	58	54.4	4.7	9.3	13.4	5.8	13.0	1.1	3.2	32.7
2022	1	56.2	51.4	4.6	8.5	13.2	5.25	10.7	0.9	3.4	28.6
2022	2	85.4*	77.0	7.0	14.1	19.8	8.9	13.8	1.1	5.6	60.7

Biological sampling



- 6 live tuna
- 1 dead specimen
- Elongated swimbladder
- Sb ~ 21% of body length
- Sb tilt angle $\sim 25 \pm 5$ degrees from body horizontal axis

Table 3. Parameters used in the single target detection (SED) and tracking algorithms.

SED algorithm			Tracking algorithm		
Pulse length	dB	6	Min. number of single targets in a track		3
Min/max normalized pulse length		0.7/1.5	Max number of pings in a track	pings	3
Maximum beam compensation	dB	15	Maximum gap between single targets	pings	5
Maximum standard deviation of axis angles	degrees	0.6	Exclusion distance (major axis/minor axis/range)	m	4/4/0.1

Data analysis

6 live tuna for **TS-length** relationship

- **SED** for TS analysis
- **Target tracking** for fish orientation

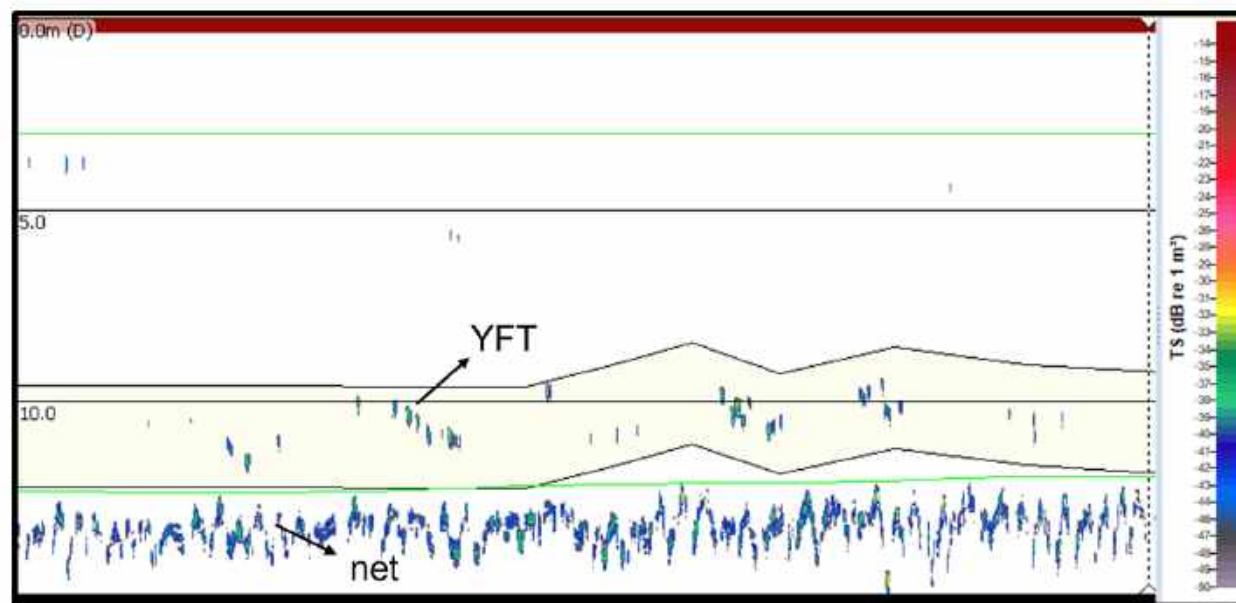
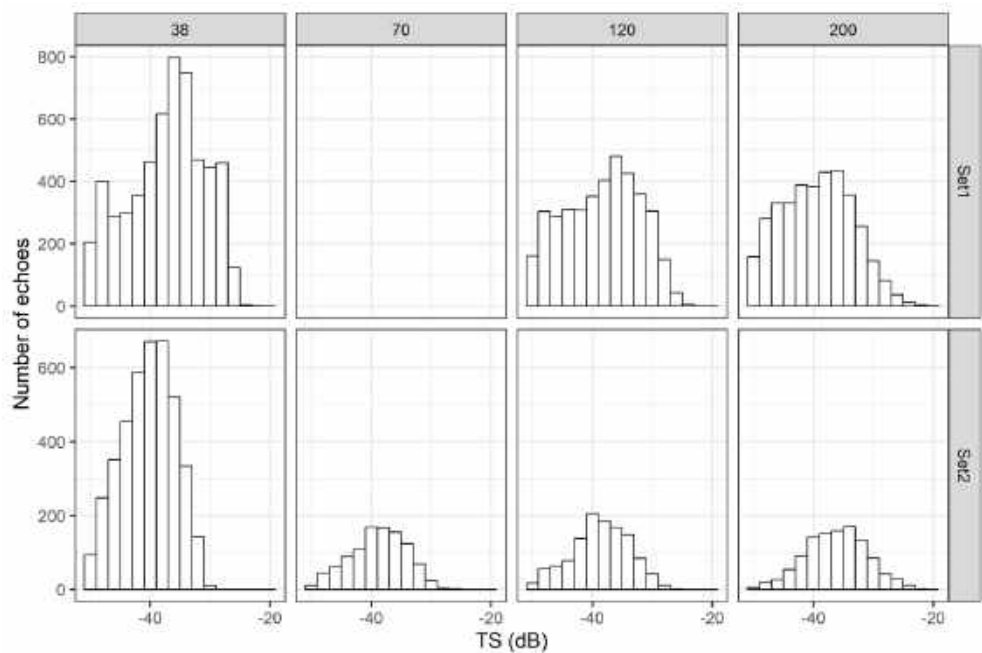


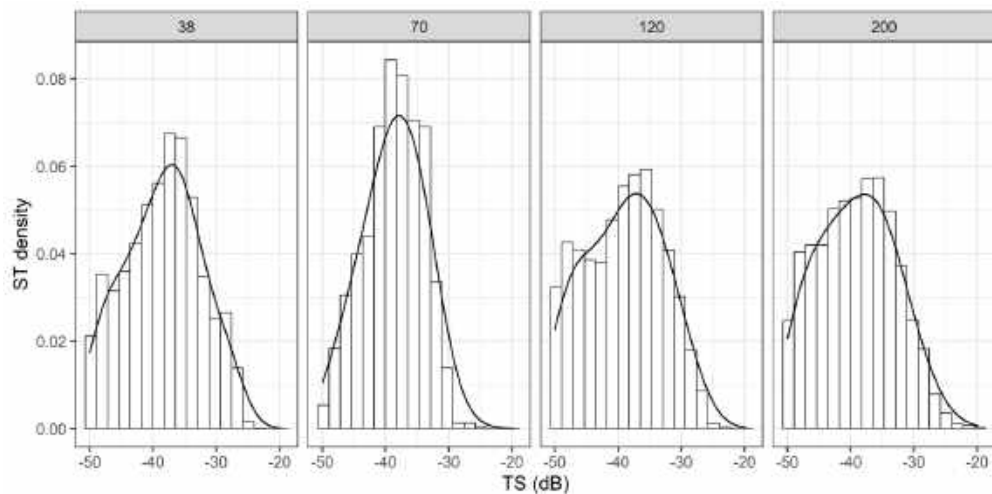
Figure 3. 38 kHz echogram showing the yellowfin tuna echoes close to the bottom of the cage.

Results

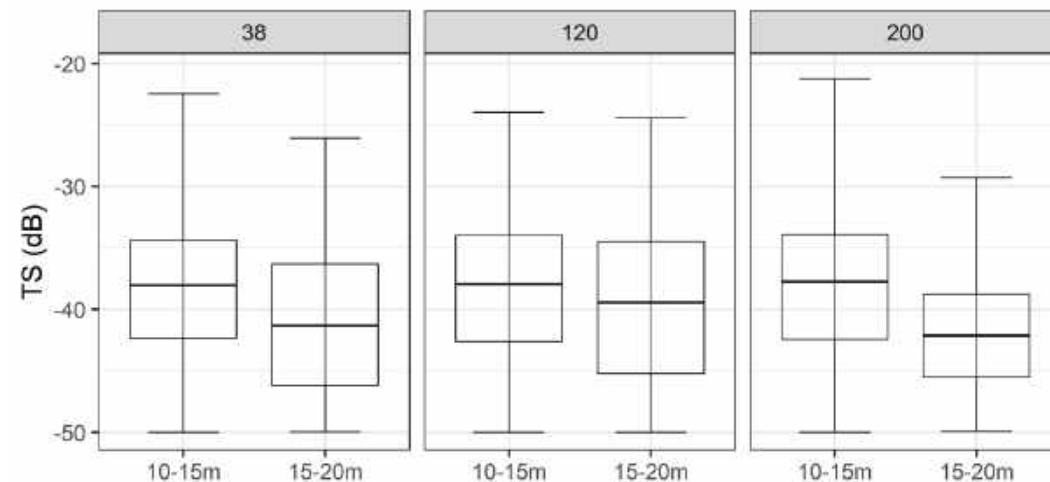
TS



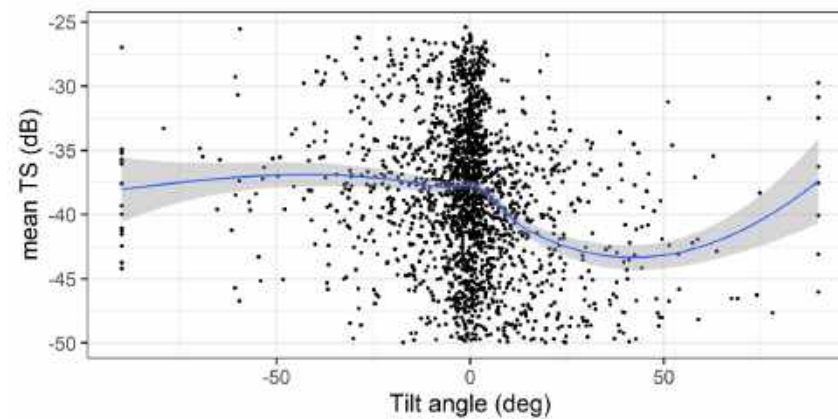
TS-smoothed



TS-depth

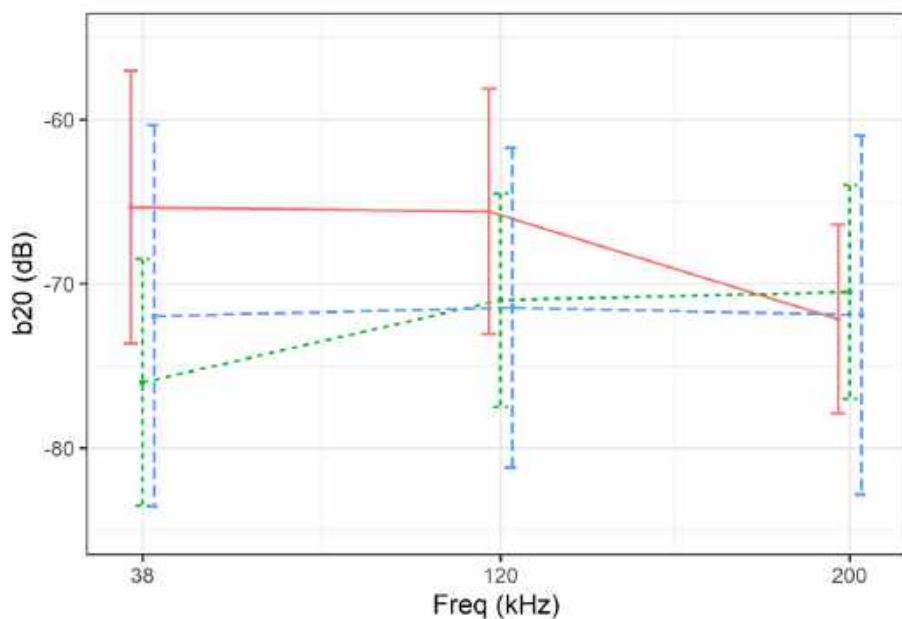


TS-tilt



Discrimination algorithm

Frequency response



$$\begin{cases}
 \text{SKJ,} & \text{if} & \begin{cases} MVBS_{38} - MVBS_{200} < A \\ MVBS_{38} - MVBS_{120} < B \end{cases} \\
 \text{BET,} & \text{if} & \begin{cases} MVBS_{38} - MVBS_{200} > C \\ MVBS_{120} - MVBS_{200} > D \end{cases} \\
 \text{YFT,} & \text{if} & \begin{cases} A < MVBS_{38} - MVBS_{200} < C \\ MVBS_{120} - MVBS_{200} < D \end{cases}
 \end{cases}$$

Optimized thresholds

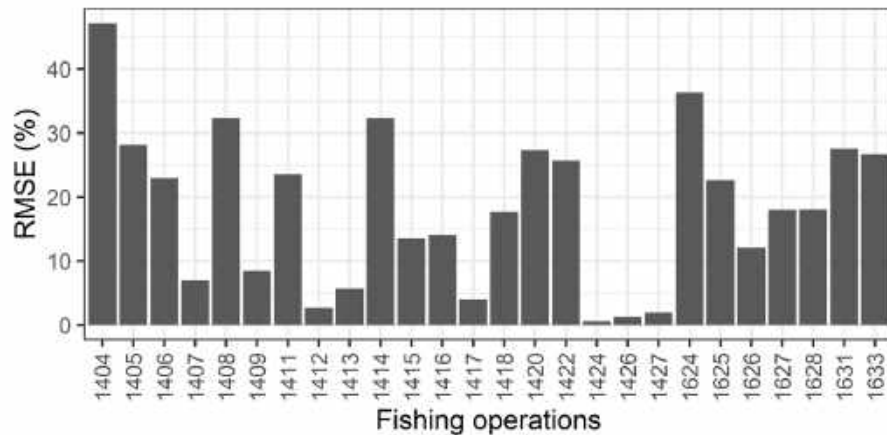
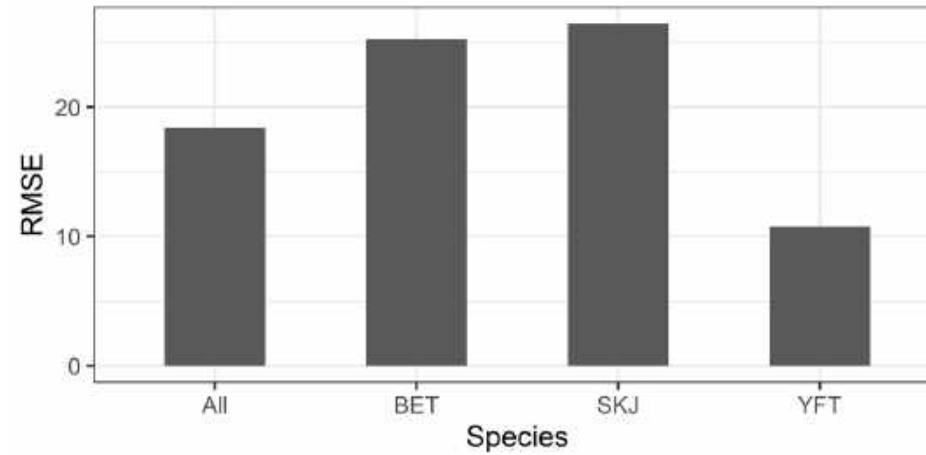
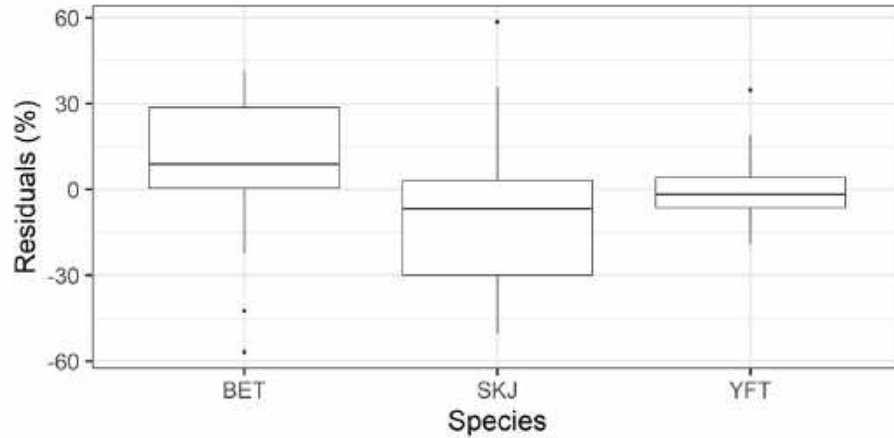
$$A = -1.6$$

$$B = -0.16$$

$$C = 0.16$$

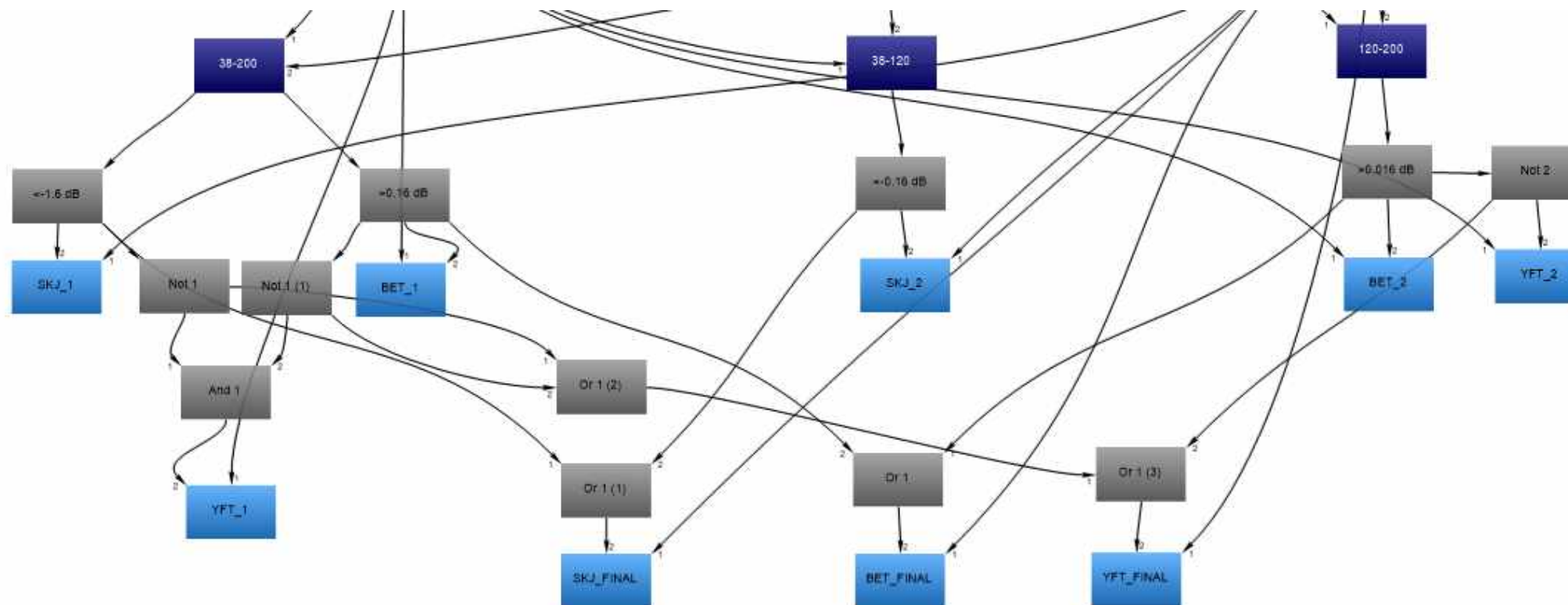
$$D = 0.016$$

Discrimination algorithm

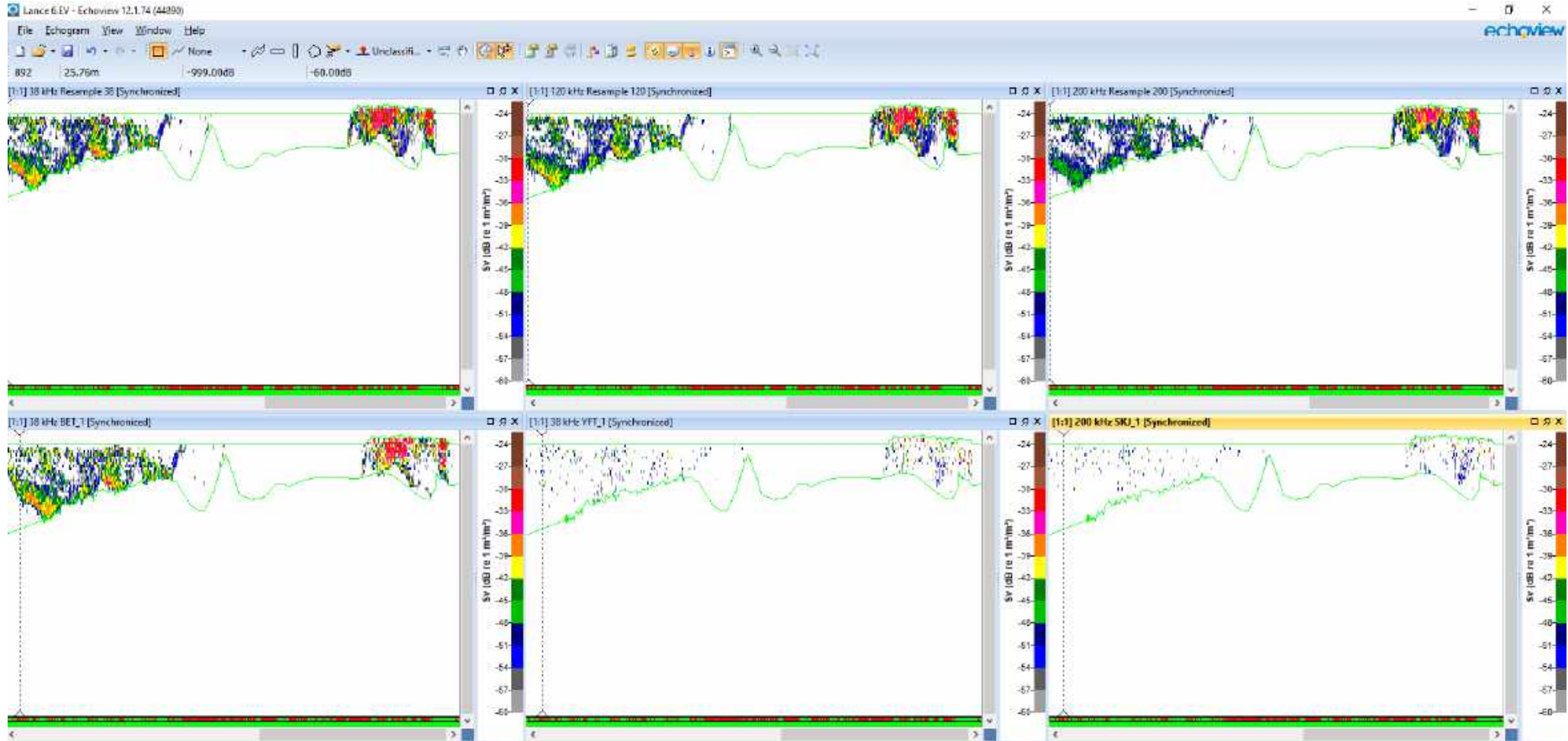


26 trawls from commercial
tuna vessels to optimize
thresholds by RMSE

Discrimination algorithm



Discrimination algorithm



Conclusions

- Discrimination algorithm is able to classify echoes into 3 tuna species BET, YFT and SKJ with an overall performance defined by RMSE < 25%. Of these 3 species, YFT was the most accurately classified (RMSE ~11%)
- Could be implemented on buoys and tuna vessels to allow fishermen to choose on which FAD to target or what is the species composition in the water before setting the gear, improving selectivity of the fishery.
- We hope that such studies, which promote in-depth exploration of the acoustic characteristics of the major tropical tuna species, will help to further refine and improve the new abundance indices based on acoustic data.

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Thank you